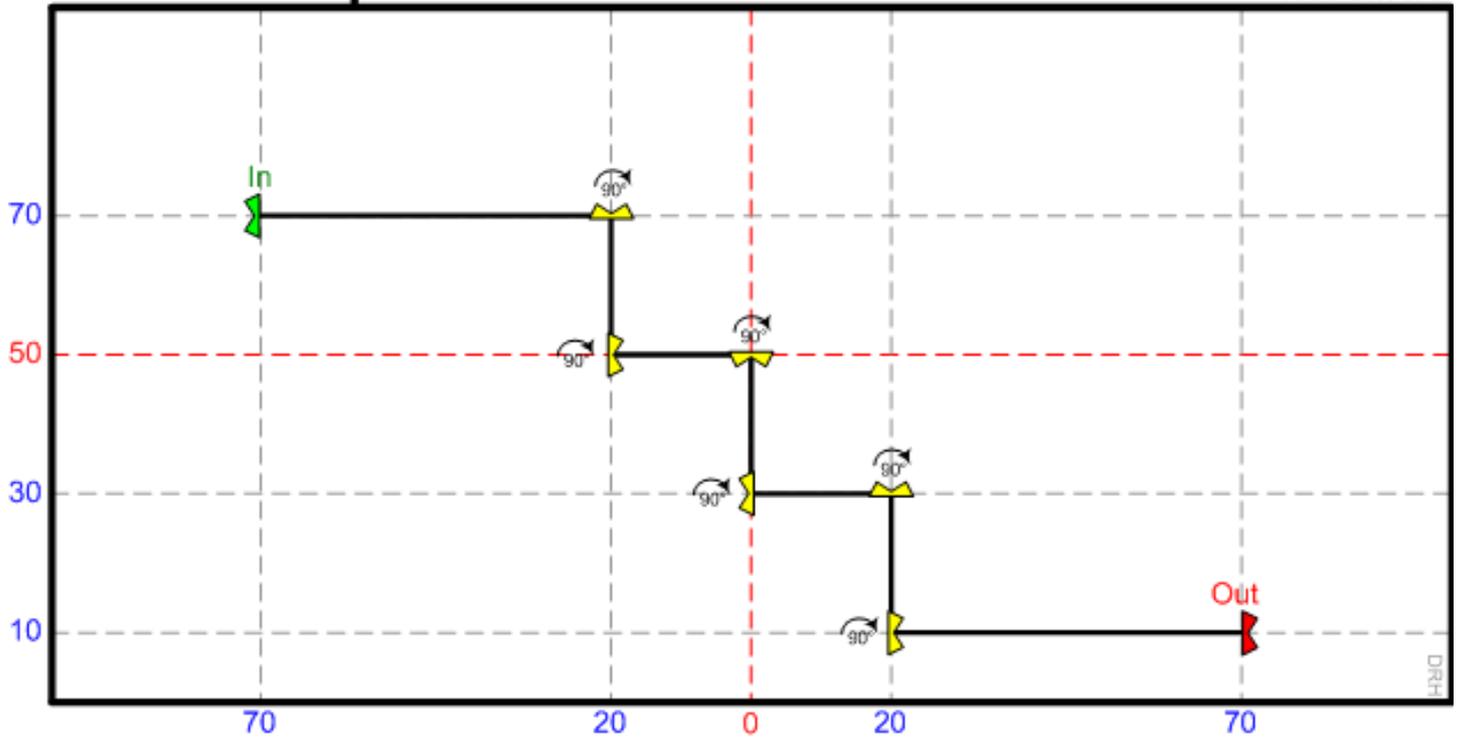


MI 03 - Steps and Turns

Version 2005-07-07



Version 2005-08-01

MI 03 – Steps and Turns

Judges will Particularly Consider

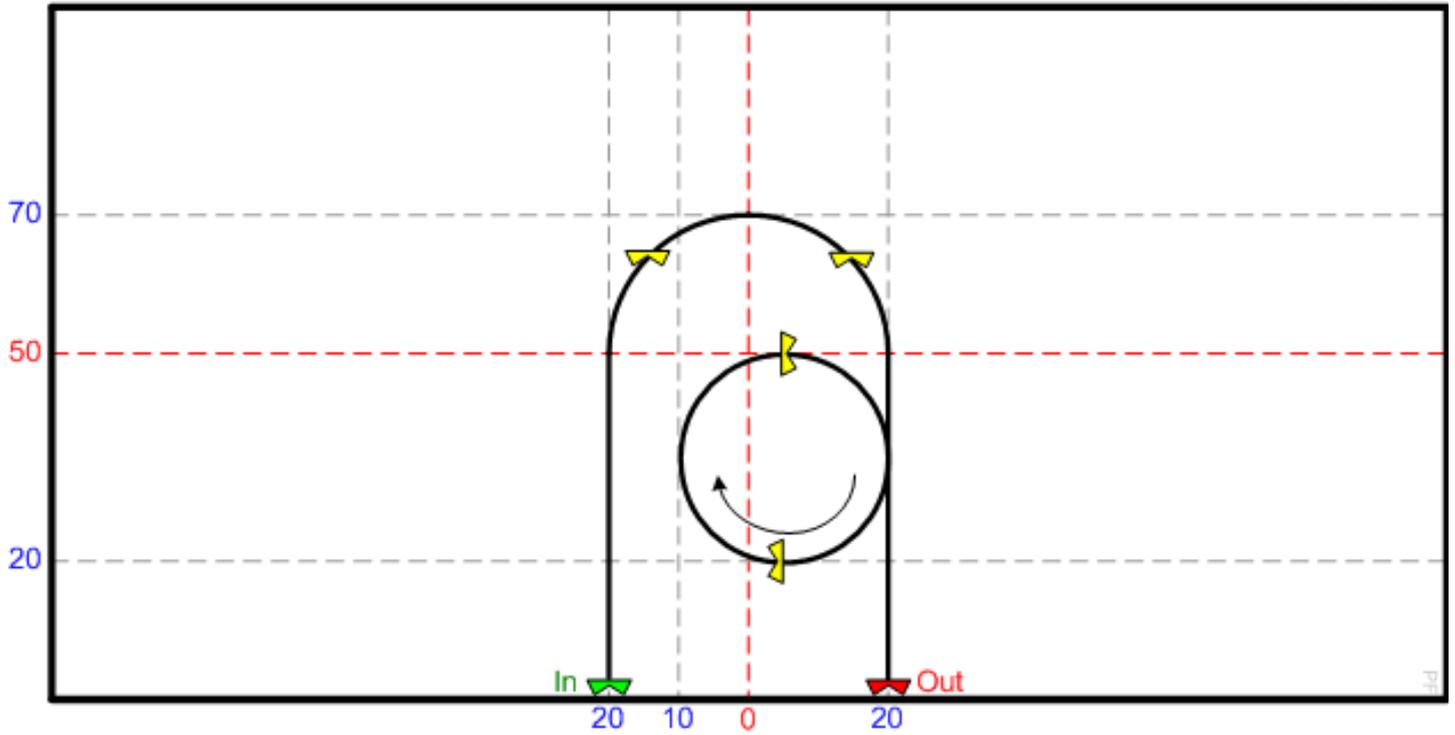
- Relative placement of components
- Rotation
- Straight lines
- Position within the precision grid
- Backward flight

Explanation

The kite rotates 90° clockwise around its center at each change of direction.

MI 07 - Arc Circle

Version 2005-07-07



2005-07-07

MI 07 – Arc Circle *Version*

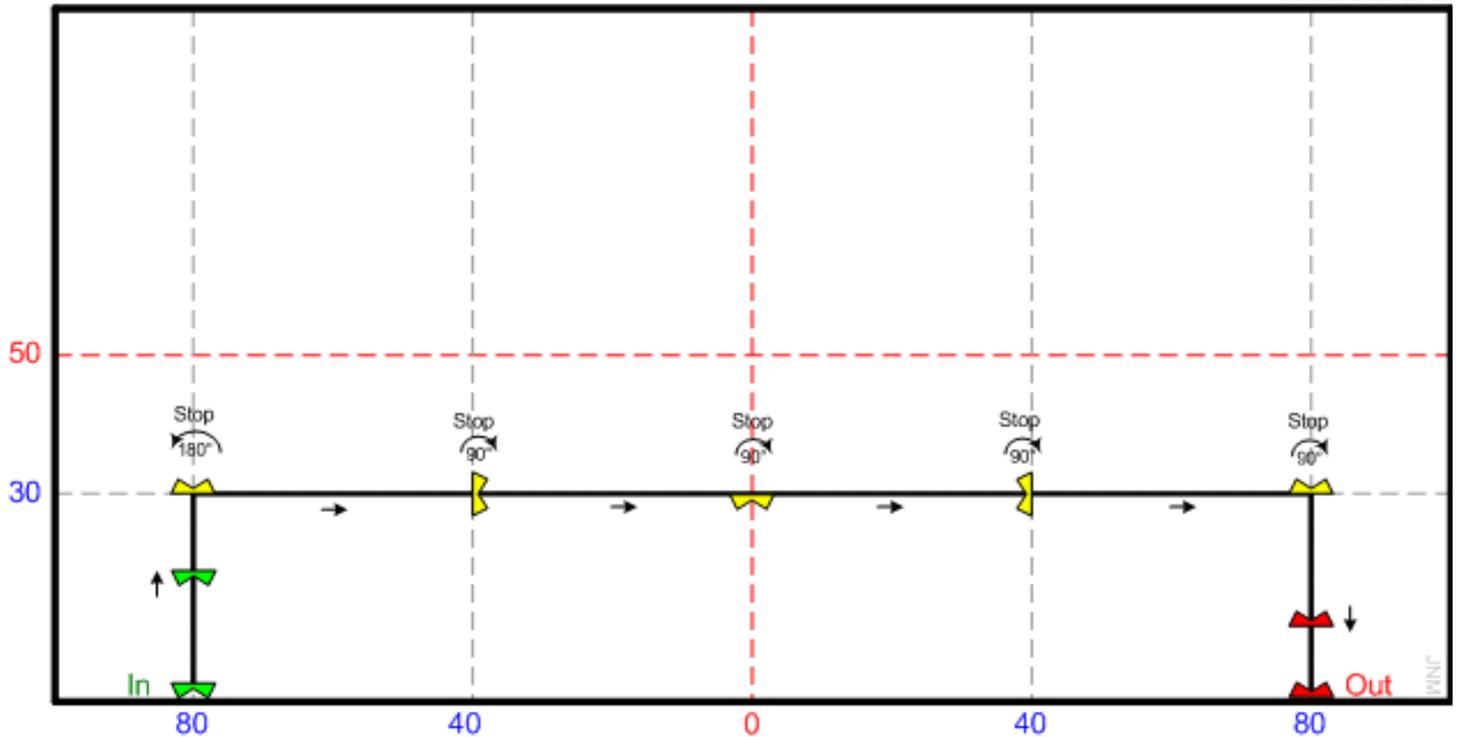
Judges will Particularly Consider

- Circle
- Backward flight
- Arc
- Launch
- Landing

Explanation

MI 15 - Pivots

Version 2005-07-07



Version 2006-06-30

MI 15 - Pivots

Judges will Particularly Consider

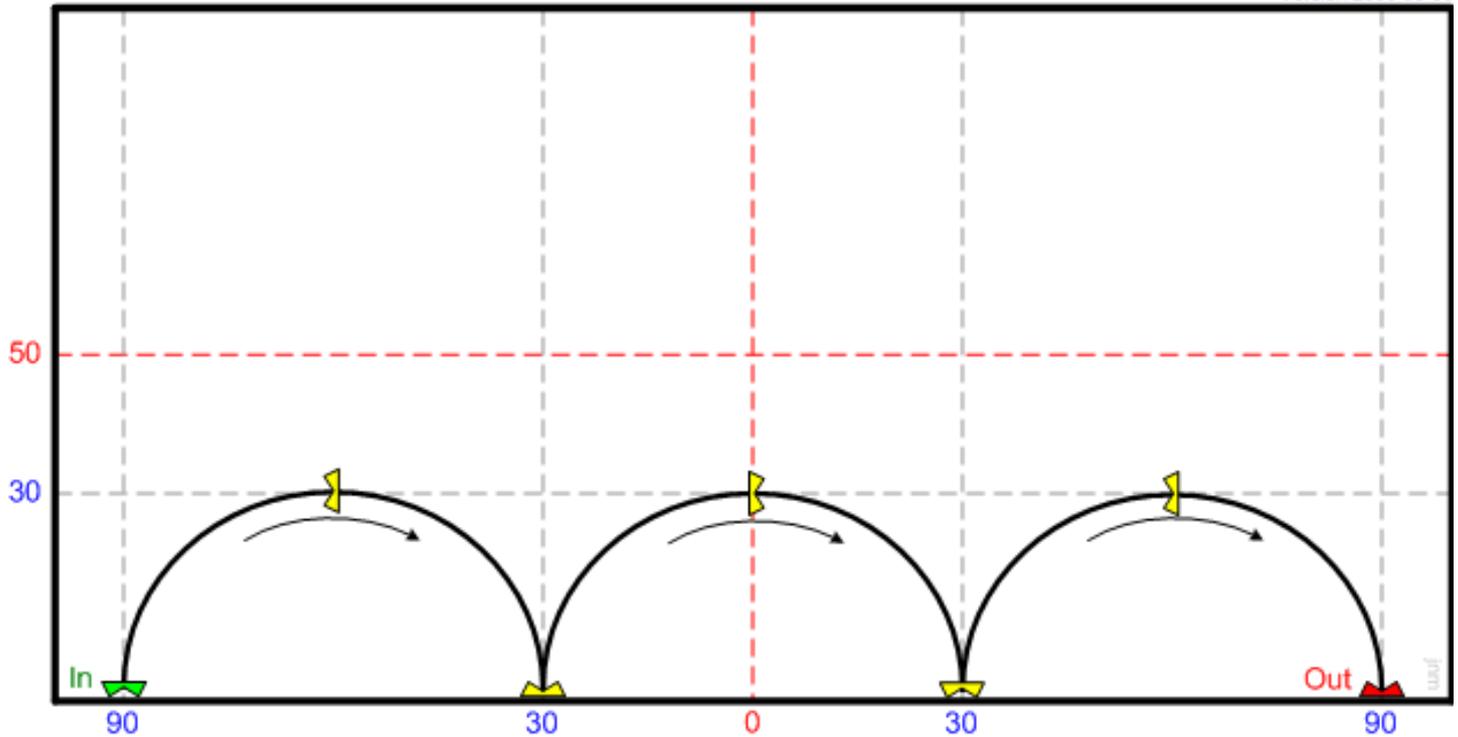
- Rotation
- Horizontal line
- Inverted slide
- Backward flight
- Slide
- Forward flight

Explanation

The kite flies to each position in the drawing, stops, rotates, and continues. The stops must be distinct. The first rotation is counterclockwise. All other rotations are clockwise.

MI 19 - Bumps

Version 2006-06-30



Version 2006-06-30

MI 19 - Bumps

Judges will Particularly Consider

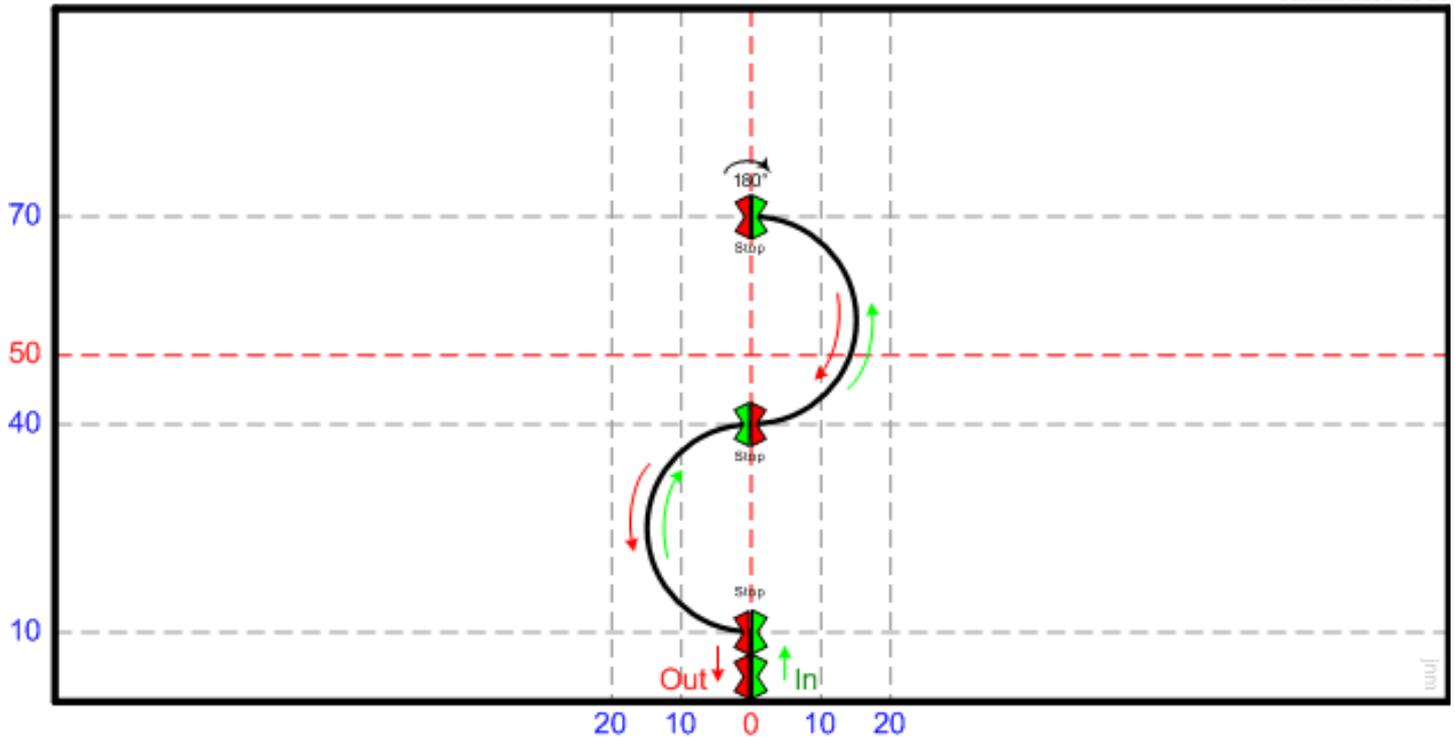
- Arcs
- Speed Control
- Landings
- Relative placement of the components
- Launch
- Position within the precision grid

Explanation

Three identically shaped and symmetrical arcs will be flown. The 1st will be flown forwards. The 2nd will be flown backwards. The 3rd will be flown forwards. All landings will be smooth and clean.

MI 22 - The Felix

Version 2006-06-30



Version 2006-06-30

MI 22 – The Felix

Judges will Particularly Consider

- Arcs
- Speed Control
- Relative placement of components
- Rotation
- Position within the precision grid

Explanation

The arcs will be flown in a forward direction.

IN is at center of the grid on the ground. The kite flies vertically to 10% and stops. The kite flies in an upward arc, vertically and to the left, to 40% and stops. The kite then flies an upward arc, vertically and to the right, to 70% and stops. The kite then rotates 180° clockwise and retraces the previous track, stopping at 40% continuing down to 10% and stops. The kite then slides vertically down to land on the right wing tip in the center of the grid. **OUT**